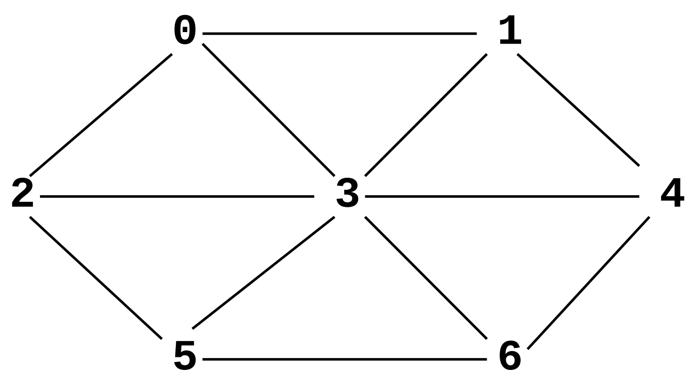
18-0: **Spanning Trees**

- Given a connected, undirected graph $G$
  - A *subgraph* of $G$ contains a subset of the vertices and edges in $G$
  - A *Spanning Tree* $T$ of $G$ is:
    - subgraph of $G$
    - contains all vertices in $G$
    - connected
    - acyclic

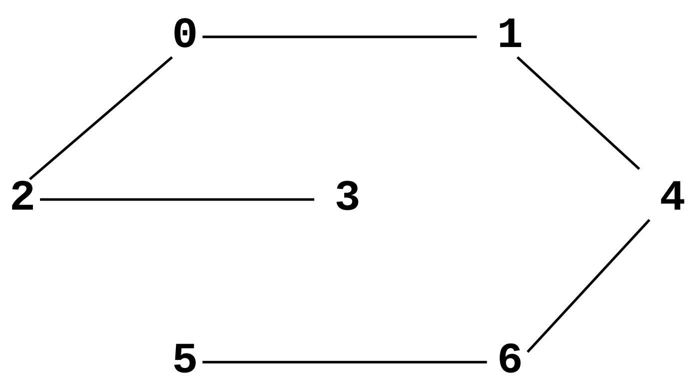
18-1: **Spanning Tree Examples**

- Graph



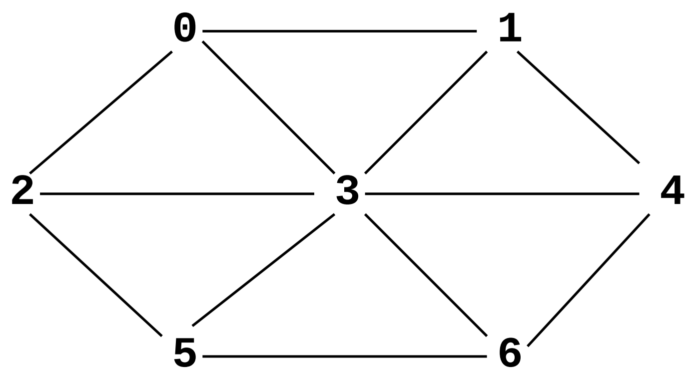

18-2: **Spanning Tree Examples**

- Spanning Tree



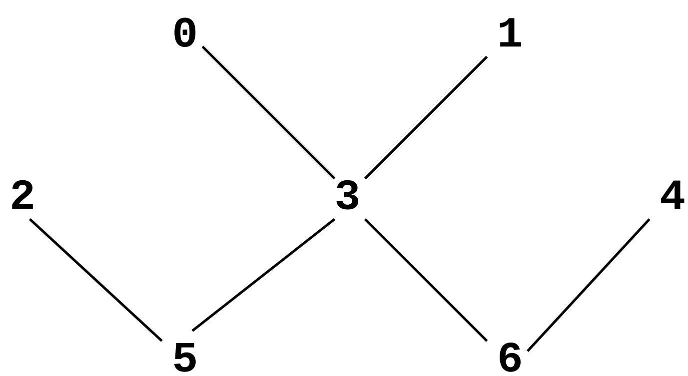

18-3: **Spanning Tree Examples**

- Graph




18-4: **Spanning Tree Examples**

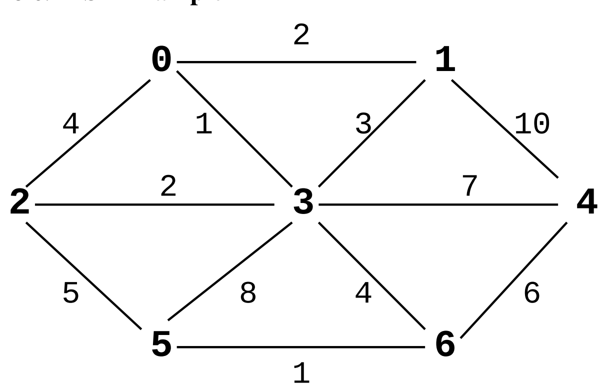
- Spanning Tree



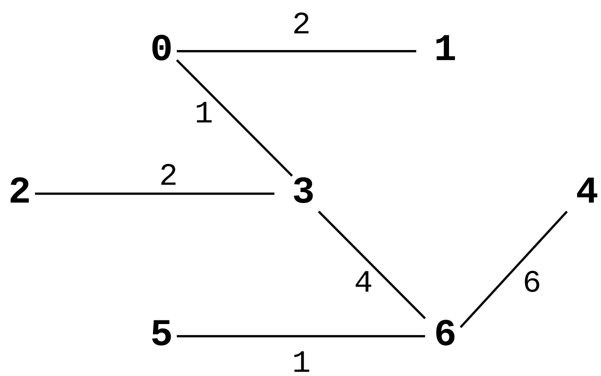

18-5: **Minimal Cost Spanning Tree**

- Minimal Cost Spanning Tree
  - Given a weighted, undirected graph $G$
  - Spanning tree of $G$ which minimizes the sum of all weights on edges of spanning tree

18-6: **MST Example**




18-7: **MST Example**




18-8: **Minimal Cost Spanning Trees**

- Can there be more than one minimal cost spanning tree for a particular graph?

18-9: **Minimal Cost Spanning Trees**

- Can there be more than one minimal cost spanning tree for a particular graph?
- YES!
  - What happens when all edges have unit cost?

18-10: **Minimal Cost Spanning Trees**

- Can there be more than one minimal cost spanning tree for a particular graph?
- YES!
  - What happens when all edges have unit cost?
  - All spanning trees are MSTs

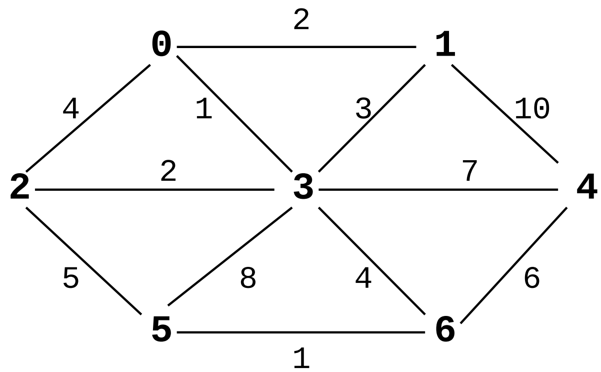
18-11: **Calculating MST**

- Two algorithms to calculate MST:
  - Kruskal's Algorithm
    - Build a "forest" of spanning trees
    - Combine into one tree
  - Prims Algorithm
    - Grow a single tree out from a start vertex

18-12: **Kruskal's Algorithm**

- Start with an empty graph (no edges)
- Sort the edges by cost
- For each edge $e$ (in increasing order of cost)
  - Add $e$ to $G$ if it would not cause a cycle

18-13: **Kruskal's Algorithm Examples**




18-14: **Kruskal's Algorithm**

- Proof (by contradiction)
- Assume that *no* optimal MST $T$ contains the minimum cost edge $e$
- Add $e$ to $T$, which causes a cycle
- Remove an edge other than $e$ to break the cycle
- cost $T' \leq T$, a contradiction

18-15: **Kruskal's Algorithm**

- Coding Kruskal's Algorithm:
  - Place all edges into a list
  - Sort list of edges by cost
  - For each edge in the list
    - Select the edge if it does not form a cycle with previously selected edges
    - How can we do this?

18-16: **Kruskal's Algorithm**

- Determining of adding an edge will cause a cycle
  - Start with a forest of $V$ trees (each containing one node)
  - Each added edge merges two trees into one tree
  - An edge causes a cycle if both vertices are in the same tree
    - (examples)

18-17: **Kruskal's Algorithm**

- We need to:
  - Put each vertex in its own tree
  - Given any two vertices $v_1$ and $v_2$, determine if they are in the same tree
  - Given any two vertices $v_1$ and $v_2$, merge the tree containing $v_1$ and the tree containing $v_2$

- ... sound familiar?

18-18: **Kruskal's Algorithm**

- Disjoint sets!
- Create a list of all edges
- Sort list of edges
- For each edge $e = (v_1, v_2)$ in the list
  - if FIND($v_1$) != FIND($v_2$)
    - Add $e$ to spanning tree
    - UNION($v_1, v_2$)

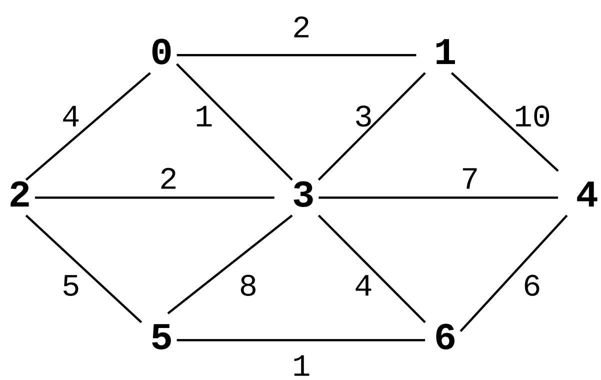
18-19: **Prim's Algorithm**

- Grow that spanning tree out from an initial vertex
- Divide the graph into two sets of vertices
  - vertices in the spanning tree
  - vertices *not* in the spanning tree
- Initially, Start vertex is in the spanning tree, all other vertices are not in the tree
  - Pick the initial vertex arbitrarily

18-20: **Prim's Algorithm**

- While there are vertices not in the spanning tree
  - Add the cheapest vertex to the spanning tree

18-21: **Prims's Algorithm Examples**




18-22: **Prim's Algorithm**

- Use a table – much like Dijkstra table
- Path has the same meaning
- Cost is for vertex $v_k$

- cost to add $v_k$ to the tree
- (instead of length of path to $v_k$)

18-23: **Prim's Algorithm**

- Code for Prim's algorithm is very similar to the code for Dijkstra's algorithm
- Make *one small change* to Dijkstra's algorithm to get Prim's algorithm

18-24: **Dijkstra Code**

```
void Dijkstra(Edge G[], int s, tableEntry T[]) {
  int i, v;
  Edge e;
  for(i=0; i<G.length; i++) {
    T[i].distance = Integer.MAX_VALUE;
    T[i].path = -1;
    T[i].known = false;
  }
  T[s].distance = 0;
  for (i=0; i < G.length; i++) {
    v = minUnknownVertex(T);
    T[v].known = true;
    for (e = G[v]; e != null; e = e.next) {
      if (T[e.neighbor].distance >
            T[v].distance + e.cost) {
        T[e.neighbor].distance = T[v].distance + e.cost;
        T[e.neighbor].path = v;
      }
    }
  }
}
```

18-25: **Prim Code**

```
void Dijkstra(Edge G[], int s, tableEntry T[]) {
  int i, v;
  Edge e;
  for(i=0; i<G.length; i++) {
    T[i].distance = Integer.MAX_VALUE;
    T[i].path = -1;
    T[i].known = false;
  }
  T[s].distance = 0;
  for (i=0; i < G.length; i++) {
    v = minUnknownVertex(T);
    T[v].known = true;
    for (e = G[v]; e != null; e = e.next) {
      if (T[e.neighbor].distance >
            e.cost) {
        T[e.neighbor].distance = e.cost;
        T[e.neighbor].path = v;
      }
    }
  }
}
```