Game Engineering 2D Midterm 1 problems Fall 2010

1. Give the ouput of the following C# Program:

```
struct s1
{
  int x;
  int y;
}
class C1
   s1 str;
}
struct S2
{
   s1 str1;
   c1 cls;
}
class Program
    void twiddle1(S2 str)
       str.str1.x = 1;
       str.str1.y = 2;
       str.cls.str.x = 3;
       str.cls.str.y = 4;
    }
    void twiddle2(S2 var str)
    {
       str.str1.x = 5;
       str.str1.y = 6;
       str.cls.str.x = 7;
       str.cls.str.y = 8;
    }
    public static void main(string[] args)
    {
         S2 str = new S2();
```

```
str.str1 = new S1();
            str.cls = new C1();
            str.cls.str = new S1();
            twiddle1(str);
            Console.Println(str.str1.x);
            Console.Println(str.str1.y);
            Console.Println(str.cls.str.x);
            Console.Println(str.cls.str.y);
            twiddle2(str);
            Console.Println(str.str1.x);
            Console.Println(str.str1.y);
            Console.Println(str.cls.str.x);
            Console.Println(str.cls.str.y);
      }
  }
  Output:
  0
  0
  3
  4
  5
  6
  7
  8
2. The following function is supposed to insert an element into a sorted linked list. It is,
  however, buggy. Fix the errors.
  class ListElem
  {
     public int data;
     public ListElem next;
     public ListElem prev;
  }
  class List
```

ListElem first;
ListElem last;

void Insert(int data)

```
ListElem e = new ListElem();
     if (first == null)
        first = new ListElem();
        last = new ListElem();
        first.data = data;
     }
     ListElem tmp = first;
     while (tmp.data > elem)
         tmp = tmp.next;
     }
     e.prev = tmp.prev;
     e.next = tmp;
     tmp.prev = e;
     tmp.prev.next = e;
  }
}
```

So many errors ...

- In the special case for inserting into an empty list, last and first should be assigned to the same value.
- In the special case for inserting into an empty list, you should not *also* fall through to the general case for inserting into a non-empty list
- The while loop will fall off the end of the list when inserting an element at the end of the list
- Need to set the first / last pointers when inserting at the front / end of of the list

There is more than one way to fix these bugs, here is one:

```
class ListElem
{
   public int data;
   public ListElem next;
   public ListElem prev;
}
class List
{
   ListElem first;
   ListElem last;
   void Insert(int data)
```

```
{
     ListElem e = new ListElem();
     e.data = data;
     if (first == null)
     {
        first = e;
        last = e;
     }
     else
     {
         if (first.data <= data)</pre>
         {
              e.next = first;
              first.prev = e;
              first = e;
         }
         else
         {
              ListElem tmp = first;
              while (tmp.next != null && tmp.next.data < data)</pre>
              {
                  tmp = tmp.next;
              }
              e.next = tmp.next;
              e.prev = tmp;
              tmp.next = e;
              if (e.next == null)
              {
                  last = e;
              }
              else
              {
                  e.next.prev = e;
              }
         }
     }
 }
}
```

3. A robot has an orientation defined by the matrix M_r and position p_r , in global space. The robot's hand has an orientation and position defined by M_h and p_h in the local space of the robot. The robot is grasping a gun, which is at orientation and position M_g and p_g in the local space of the hand of the robot. Give the position and orientation of the gun in Global Space.

Position of gun in world space: $(p_g * M_h + p_h) * M_r + p_r$

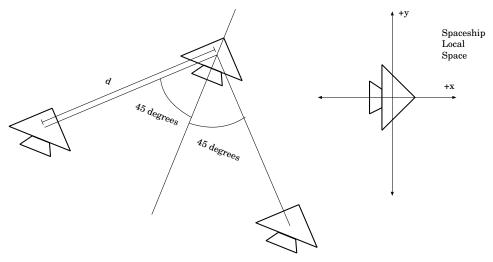
Orientation of gun in world space: $M_g * M_h * M_r$

4. A spaceship s has an orientation defined by the following rotational matrix:

$$M = \left[\begin{array}{cc} a & b \\ c & d \end{array} \right]$$

and position p = [x, y].

The spaceship points down the x axis in its local space. The ship is flying in formation with two ships s_2 and s_3 that are at a distance d_1 away, each at a 45 degree angle from the original ship:



Give the orientations (as rotational matrices) and positions of s_2 and s_3 , as a function of a, b, c, d, x, y.

First, we will look at the orientations, since those are easiest: The orientation of the ships are the same as the orientation of the original ship:

$$M = \left[\begin{array}{cc} a & b \\ c & d \end{array} \right]$$

The vectors from the lead ship to each of the following ships (in the local space of the lead ship) are $d * \left[\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}\right]$ and $d_1 * \left[\frac{-1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}\right]$. In global space, those vectors are

$$d_1 * \left[\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}} \right] \left[\begin{array}{cc} a & b \\ c & d \end{array} \right] = d_1 * \left[\frac{a-c}{\sqrt{2}}, \frac{b-d}{\sqrt{2}} \right]$$

and

$$d_1 * \left[\frac{-1}{\sqrt{2}}, \frac{-1}{\sqrt{2}} \right] \left[\begin{array}{cc} a & b \\ c & d \end{array} \right] = d_1 * \left[\frac{-a-c}{\sqrt{2}}, \frac{-b-d}{\sqrt{2}} \right]$$

Add each of these vectors to the position of the lead ship in global space, and you get:

$$[x,y] + d_1 * \left[\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}\right] \left[\begin{array}{cc} a & b \\ c & d \end{array}\right] = \left[x + \frac{d_1(a-c)}{\sqrt{2}}, y + \frac{d_1(b-d)}{\sqrt{2}}\right]$$

and

$$[x,y] + d_1 * \begin{bmatrix} -1 \\ \sqrt{2} \end{bmatrix}, \frac{-1}{\sqrt{2}} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} x + \frac{d_1(-a-c)}{\sqrt{2}}, y + \frac{d_1(-b-d)}{\sqrt{2}} \end{bmatrix}$$