

## 18-0: Flow Networks

- Directed Graph  $G$
- Each edge weight is a “capacity”
  - Amount of water/second that can flow through a pipe, for instance
- Single source  $S$ , single sink  $t$
- Calculate maximum flow through graph

## 18-1: Flow Networks

- Flow: Function:  $V \times V \rightarrow R$ 
  - Flow from each vertex to every other vertex
  - $f(u, v)$  is the direct flow from  $u$  to  $v$
- Properties:
  - $\forall u, v \in V, f(u, v) \leq c(u, v)$
  - $\forall u, v \in V, f(u, v) = -f(v, u)$
  - $\forall u \in V - \{s, t\}, \sum_{v \in V} f(u, v) = 0$
- Total flow,  $|f| = \sum_{v \in V} f(s, v) = \sum_{v \in V} f(v, t)$

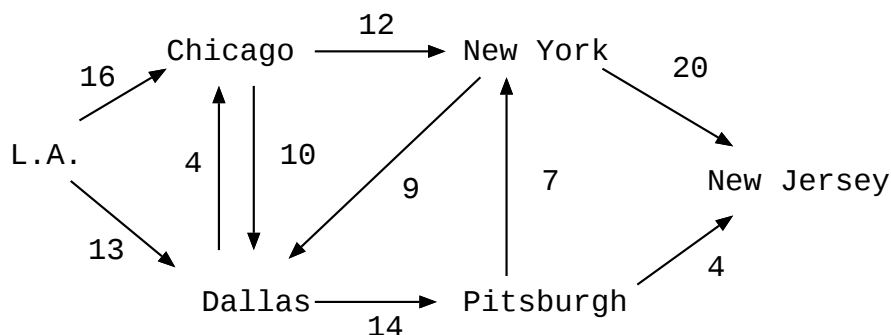
## 18-2: Flow Networks

- Single Source / Single Sink
  - Assume that there is always a single source and a single sink
  - Don't lose any expressive power – always transform a problem with multiple sources and multiple sinks to an equivalent problem with a single source and a single sink
  - How?

## 18-3: Flow Networks

- Example: Shipping product to a warehouse
  - Product produced at a factory, put in crates
  - Crates are shipped to warehouse
  - To cut down costs, use “extra space” in other people's trucks
  - How much product can be produced per day?

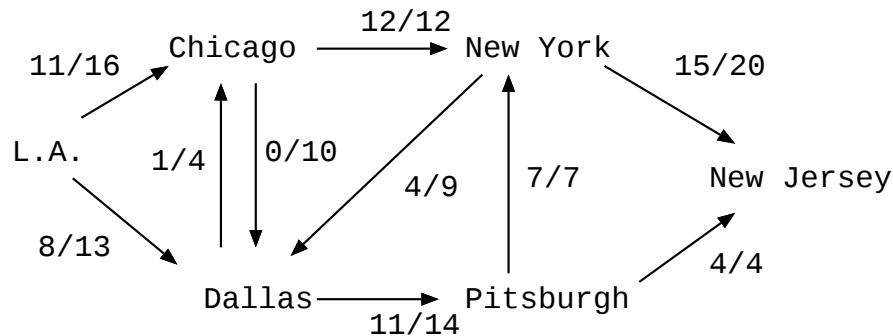
## 18-4: Flow Networks



## 18-5: Flow Networks

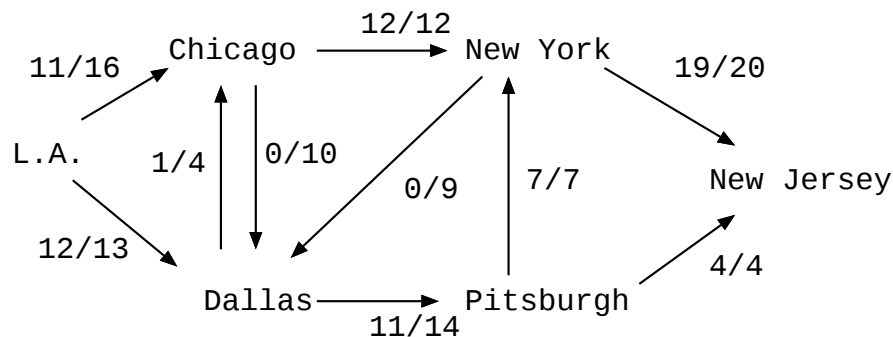
- It would be a little silly to ship 4 crates from Dallas to Chicago, and 7 crates from Chicago to Dallas
  - Could just ship 3 crates from Chicago to Dallas instead
- We will assume that there is only every flow in one direction
  - Flow in the opposite direction “cancels” out

## 18-6: Flow Networks



Is this flow optimal?

## 18-7: Flow Networks



## 18-8: Flow Networks

- Negative flow
  - It is perfectly legal for there to be a negative flow from  $v$  to  $u$
  - Negative flow from  $v$  to  $u$  just means that there is a positive flow from  $u$  to  $v$
  - Recall that the total flow over all edge incident to a vertex must be zero, except for source & sink

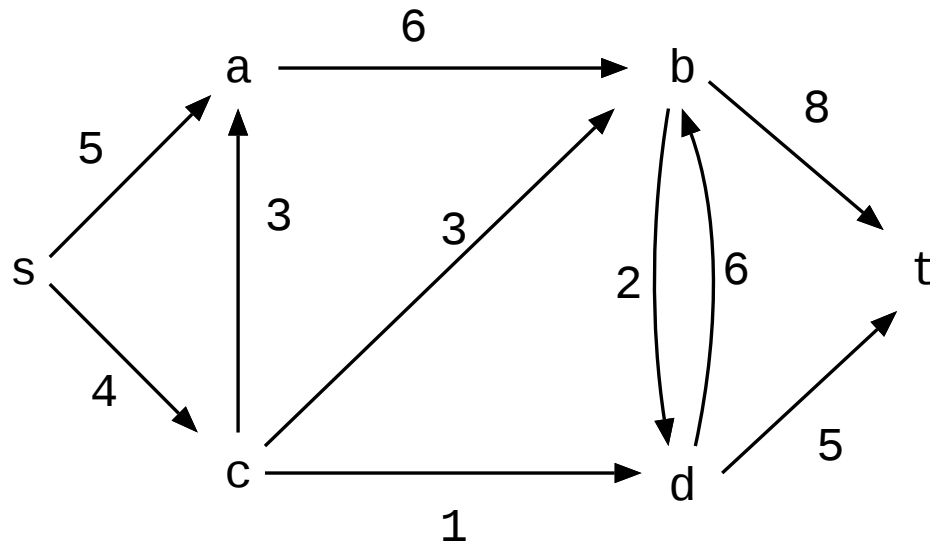
## 18-9: Flow Networks

- Residual capacity
  - $c_f(u, v)$  is the residual capacity of edge  $(u, v)$
  - $c_f(u, v) = c(u, v) - f(u, v)$
  - Note that it is possible for the residual capacity of an edge to be greater than the total capacity
    - Cancelling flow in the opposite direction

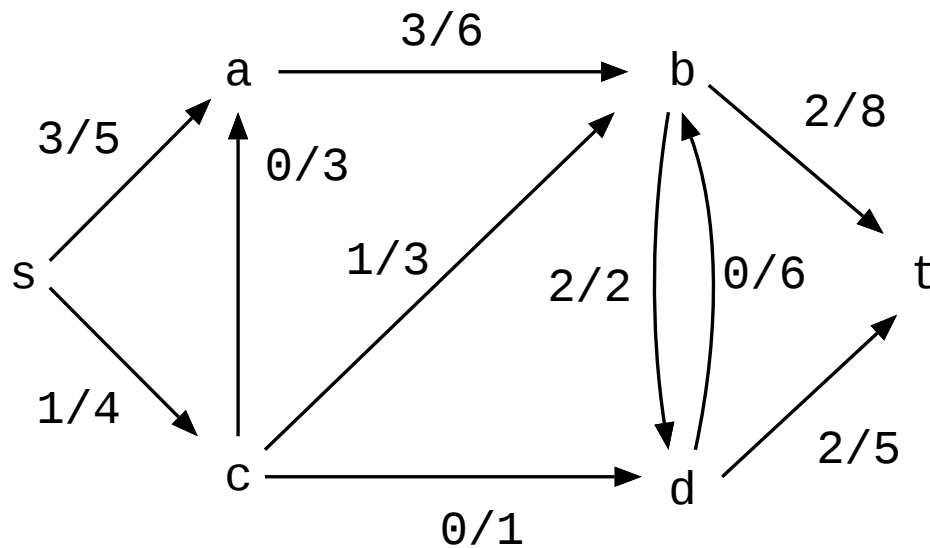
## 18-10: Flow Networks

- Residual Network
  - Given a set of capacities, and a set of current flows, we can create a residual network
  - Residual network can have different edges than the capacity network

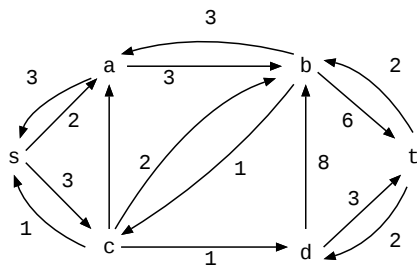
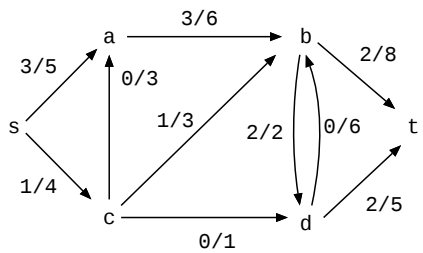
18-11: Flow Networks



18-12: Flow Networks



18-13: Flow Networks



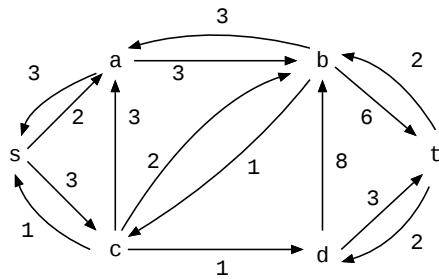
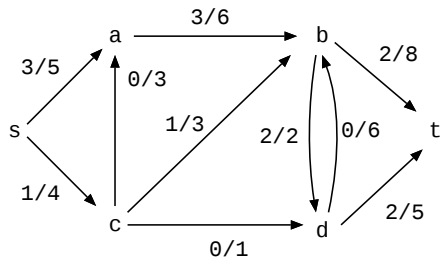
## 18-14: Flow Networks

- Given a flow network, with some flows calculated
- Induced residual network
- There is a path from source to sink in the residual network such that:
  - All residual capacities along the path are  $> 0$
- How can we increase the total flow?

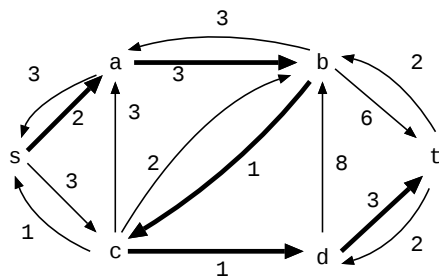
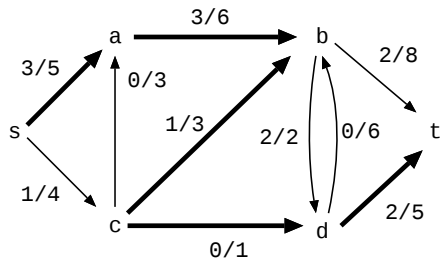
## 18-15: Augmenting Path

- An *Augmenting path* in a flow network is a path through the network such that all residual capacities along the path  $> 0$
- Given a flow network and an augmenting path, we can increase the total flow by the smallest residual capacity along the path
  - Increase flow along path by smallest residual capacity along the path
  - May involve some flow cancelling

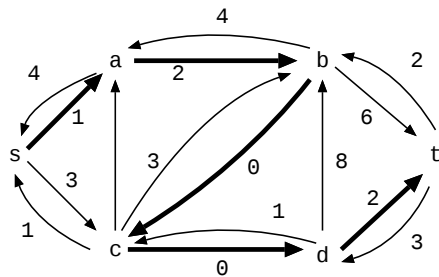
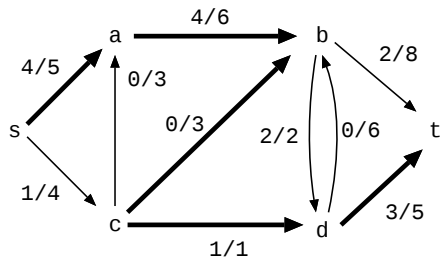
## 18-16: Augmenting Path



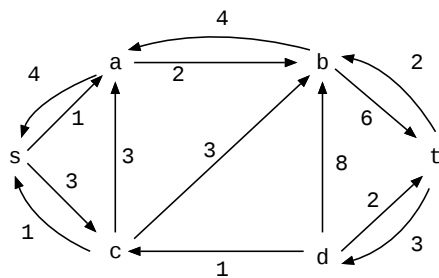
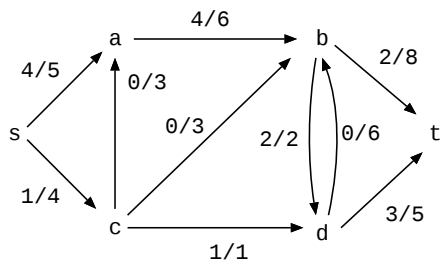
18-17: Augmenting Path



18-18: Augmenting Path



## 18-19: Augmenting Path



## 18-20: Ford-Fulkerson Method

Ford-Fulkerson( $G, s, t$ )

initialize flow  $f$  to 0

while there is an augmenting path  $p$

augment flow  $f$  along  $p$

return  $f$

## 18-21: Ford-Fulkerson Method

- What is the running time of Ford-Fulkerson Method?
- Find an augmenting path

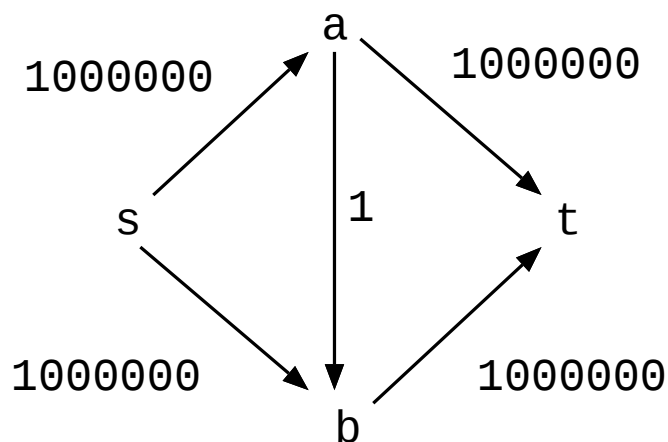
- Update flows / residuals
- Repeat until there are no more augmenting paths

18-22: **Ford-Fulkerson Method**

- What is the running time of Ford-Fulkerson Method?
  - Find an augmenting path
    - Using DFS,  $O(|E|)$
  - Update flows / residuals
    - $O(|E|)$
  - Repeat until there are no more augmenting paths
    - Each iteration could increase the flow by 1, could have  $|f|$  iterations!
- Total:  $O(|f| * |E|)$

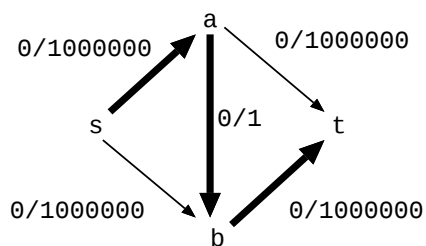
18-23: **Ford-Fulkerson Method**

- Could take as many as  $|f|$  iterations:

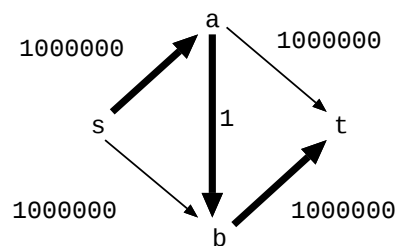
18-24: **Ford-Fulkerson Method**

- Could take as many as  $|f|$  iterations:

Flow Network

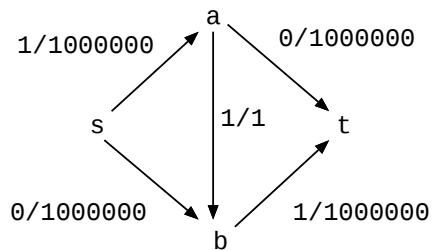


Residual Network

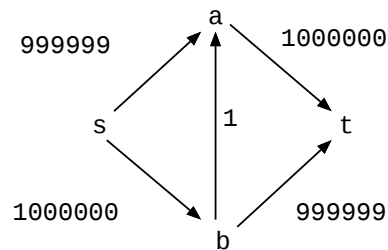
18-25: **Ford-Fulkerson Method**

- Could take as many as  $|f|$  iterations:

Flow Network



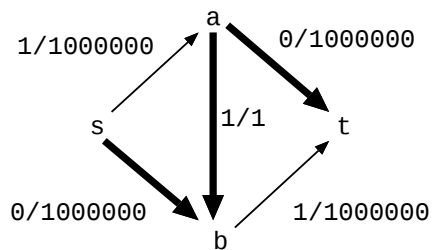
Residual Network



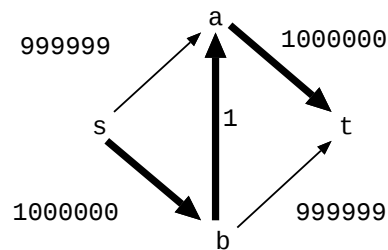
18-26: Ford-Fulkerson Method

- Could take as many as  $|f|$  iterations:

Flow Network



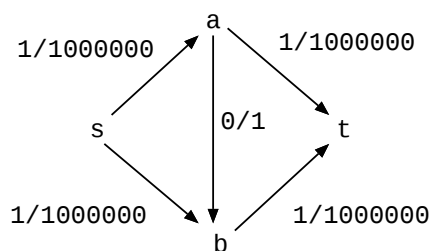
Residual Network



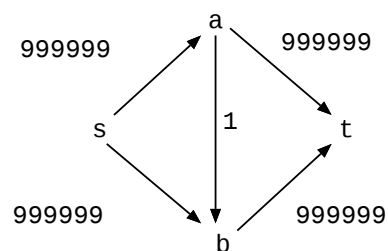
18-27: Ford-Fulkerson Method

- Could take as many as  $|f|$  iterations:

Flow Network



Residual Network



18-28: Ford-Fulkerson Method

- How can we be smart about choosing the augmenting path, to avoid the previous case?

18-29: Edmonds-Karp Algorithm

- How can we be smart about choosing the augmenting path, to avoid the previous case?
  - We can get better performance by always picking the shortest path (path with the fewest edges)

- We can quickly find the shortest path by doing a BFS from the source in the residual network, to find the shortest augmenting path
- If we always choose the shortest augmenting path (i.e., smallest number of edges), total number of iterations is  $O(|V| * |E|)$ , for a total running time of  $O(|V| * |E|^2)$

**18-30: Edmonds-Karp Algorithm**

- If we always pick the shortest augmenting path, no more than  $|V| * |E|$  iterations:
  - Lemma #1: Shortest path from source  $s$  to any other vertex in residual graph can only increase, not decrease.
    - Residual graph changes over time – edges are added and removed
    - However, shortest path from source to any vertex in the residual graph will only increase over time, never decrease

**18-31: Edmonds-Karp Algorithm**

- Lemma #1: Shortest path from source  $s$  to any other vertex in residual graph can only increase, not decrease. Proof by contradiction
  - Assume shortest path from source to some other vertex changes after an augmentation
  - Let  $f$  be the flow right before the shortest path decrease, and  $f'$  be the flow right after
  - Let  $v$  be a vertex such that  $\delta_{f'}(s, v) < \delta_f(s, v)$ . If there is more than once such  $v$ , pick the one with the smallest  $\delta_{f'}(s, v)$  value
  - Let  $p = s \rightarrow \dots \rightarrow u \rightarrow v$  be the shortest path from  $s$  to  $v$  in  $f'$

**18-32: Edmonds-Karp Algorithm**

- Lemma #1: Shortest path from source  $s$  to any other vertex in residual graph can only increase, not decrease. Proof by contradiction
  - Edge  $(u, v)$  (last edge on path from  $s$  to  $v$  in  $G_{f'}$ ) must not be in  $G_f$ 
    - $\delta_{f'}(s, u) \geq \delta_f(s, u)$ 
      - Because  $\delta_{f'}(s, u) < \delta_{f'}(s, v)$ , and we picked  $v$  to be the vertex with the smallest  $\delta_{f'}(s, v)$  value that changed
  - If  $(u, v) \in G_f$

$$\begin{aligned}
 \delta_f(s, v) &\leq \delta_f(s, u) + 1 \\
 &\leq \delta_{f'}(s, u) + 1 \\
 &\leq \delta_{f'}(s, v)
 \end{aligned}$$

**18-33: Edmonds-Karp Algorithm**

- Lemma #1: Shortest path from source  $s$  to any other vertex in residual graph can only increase, not decrease. Proof by contradiction
  - Edge  $(u, v)$  must be in  $G_{f'}$  but not in  $G_f$  – so the augmenting path must include  $(v, u)$
  - We always choose shortest paths as our augmenting path
  - Shortest path from  $s$  to  $u$  must include  $(v, u)$

$$\begin{aligned}
 \delta_f(s, v) &= \delta_f(s, u) - 1 \\
 &\leq \delta_{f'}(s, u) - 1 \\
 &\leq \delta_{f'}(s, v) - 2
 \end{aligned}$$

- Contradiction!

#### 18-34: Edmonds-Karp Algorithm

- If we always pick the shortest augmenting path, no more than  $|V| * |E|$  iterations:
  - An edge on an augmenting path is critical if it is removed when the flow is augmented (why must there always be at least one critical edge)?
  - Each edge can only be critical at most  $|V|/2$  times

#### 18-35: Edmonds-Karp Algorithm

- Each edge can only be critical at most  $|V|/2$  times
  - When edge  $(u, v)$  is critical:
    - $\delta_f(s, v) = \delta_f(s, u) + 1$
  - Critical edge is removed – before it can become critical again, it must be added back by some augmenting path – that path must contain edge  $(u, v)$
  - Let  $f'$  be the flow when the edge is added back.

$$\begin{aligned}\delta_{f'}(s, u) &= \delta_{f'}(s, v) + 1 \\ &\geq \delta_f(s, v) + 1 \\ &= \delta_f(s, u) + 1 + 1\end{aligned}$$

- If an edge  $(u, v)$  becomes critical twice, the shortest path from  $s$  to  $u$  must increase by 2
- Each edge can only be critical  $|V|/2$  times

#### 18-36: Edmonds-Karp Algorithm

- Each edge can only be critical at most  $|V|/2$  times
  - Let  $f'$  be the flow when the edge is added back.

$$\begin{aligned}\delta_{f'}(s, u) &= \delta_{f'}(s, v) + 1 \\ &\geq \delta_f(s, v) + 1 \\ &= \delta_f(s, u) + 1 + 1\end{aligned}$$

- If an edge  $(u, v)$  becomes critical twice, the shortest path from  $s$  to  $u$  must increase by 2
- Each edge can only be critical  $|V|/2$  times

#### 18-37: Edmonds-Karp Algorithm

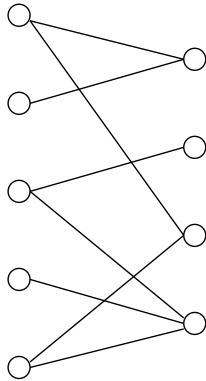
- If we always pick the shortest augmenting path, no more than  $|V| * |E|$  iterations:
  - An edge on an augmenting path is critical if it is removed when the flow is augmented (why must there always be at least one critical edge)?
  - Each edge can only be critical at most  $|V|/2$  times
  - $|E|$  total edges – no more than  $|E| * |V|/2$  iterations

## 18-38: Matching Problem

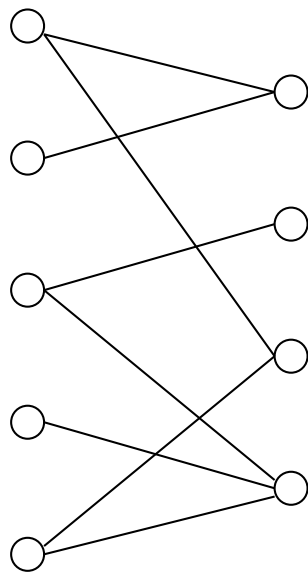
- Given an undirected graph  $G = (V, E)$  a matching  $M$  is
  - Subset of edges  $E$
  - For any vertex  $v \in V$ , at most one edge in  $M$  is incident to  $v$
- Maximum matching is a matching with largest possible number of edges

## 18-39: Matching Problem

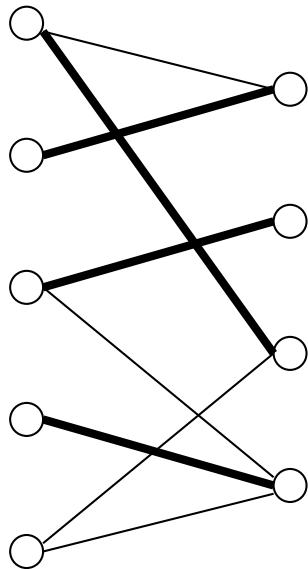
- Bipartite graph
  - Vertices can be divided into two groups,  $S_1$  and  $S_2$
  - Each edge connects a vertex in  $S_1$  with a vertex in  $S_2$



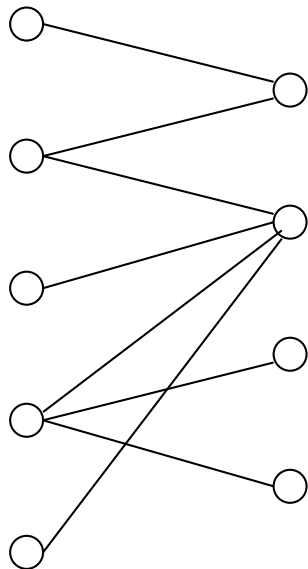
## 18-40: Matching Problem



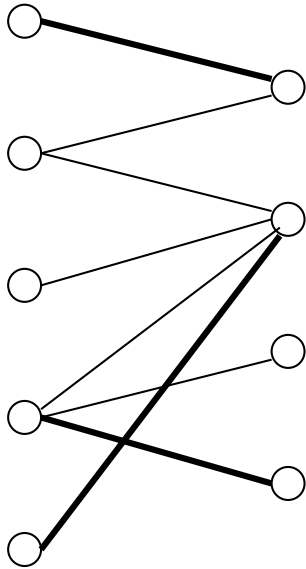
## 18-41: Matching Problem



18-42: Matching Problem

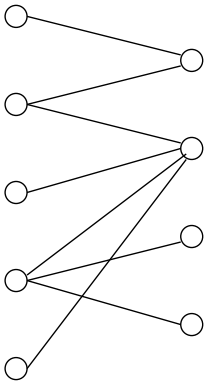


18-43: Matching Problem



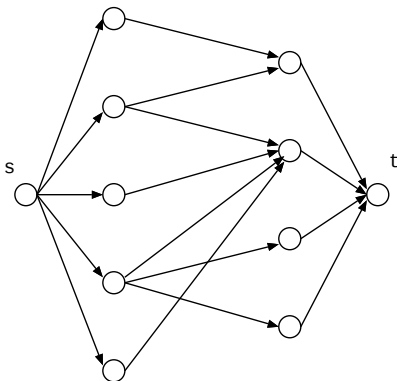
18-44: Matching Problem

- Finding a matching in a bipartite graph can be considered a maximum flow problem. How?



18-45: Matching Problem

- Finding a matching in a bipartite graph can be considered a maximum flow problem. How?



18-46: Push-Relabel Algorithms

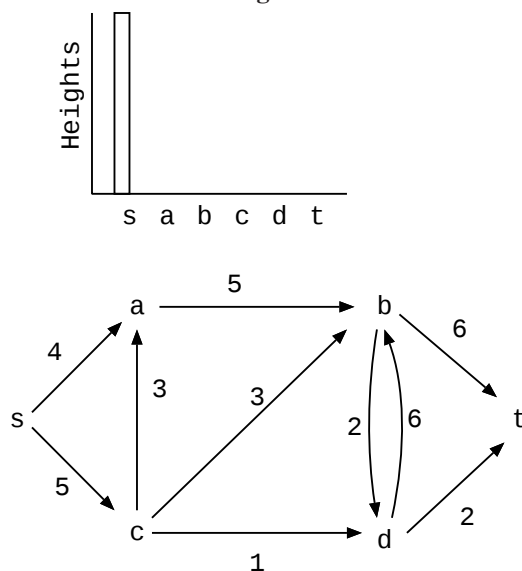
- New algorithm for calculating maximum flow
- Basic idea:
  - Allow vertices to be “overflow” (have more inflow than outflow)
  - Push full capacity out of edges from source
  - Push overflow at each vertex forward to the sink
  - Push excess flow back to source

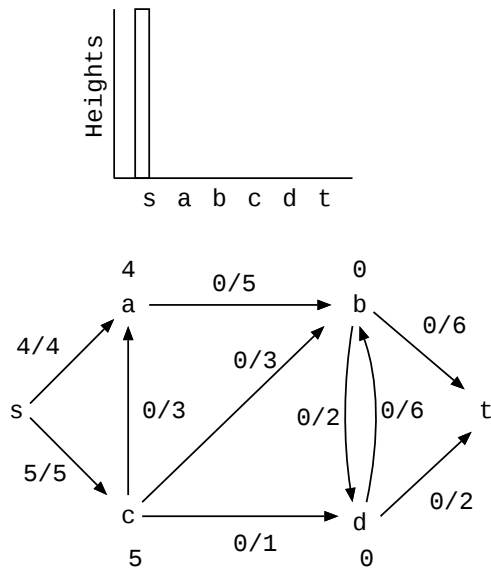
18-47: **Push-Relabel Algorithms**

- Think of graph as a bunch of water containers connected by pipes.
- We will raise and lower the vertices, and allow water to flow between them
  - Water can only flow from higher vertex to a lower vertex
- Initially, source is at height  $|V|$ , all other vertices are at height 1
- Full capacity of each pipe out of the source flows to each vertex adjacent to the source

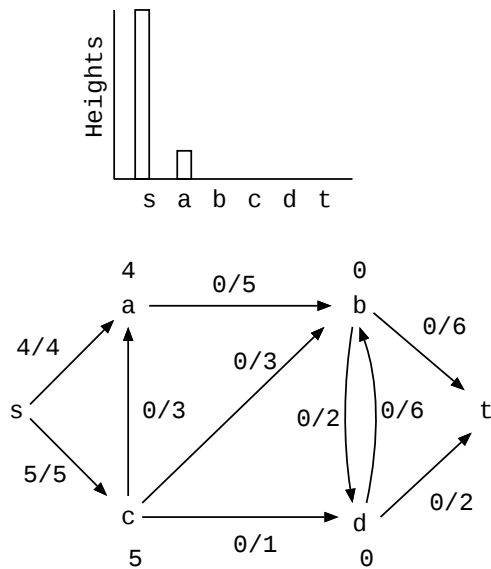
18-48: **Push-Relabel Algorithms**

- Full capacity of each pipe out of the source flows back to each vertex adjacent to the source
  - This causes some vertices to be overfull – inflow greater than outflow
- Raise some vertex whose inflow is greater than outflow, to allow water to flow to different vertices
- Repeat until all vertices (other than the sink, which stays at level 0) are at the same level as the source
- If there are still overfull vertices, continue to raise them so that the extra flow spills back into the source

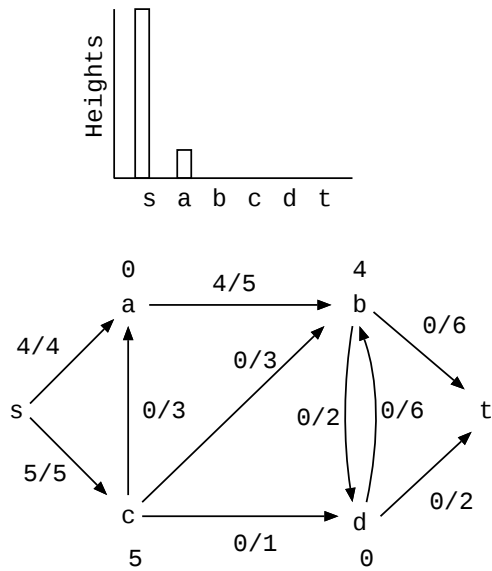
18-49: **Push-Relabel Algorithms**18-50: **Push-Relabel Algorithms**



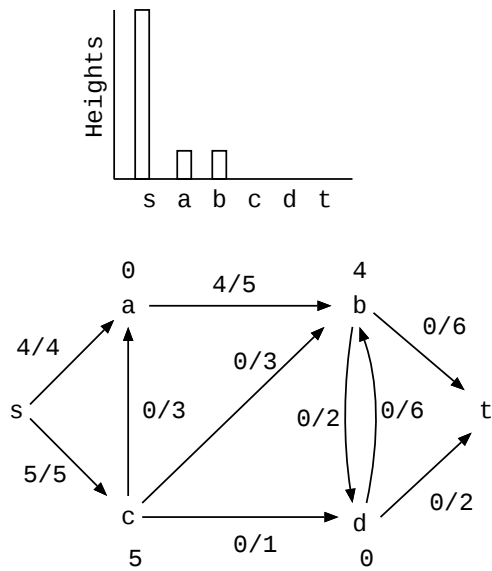
18-51: Push-Relabel Algorithms



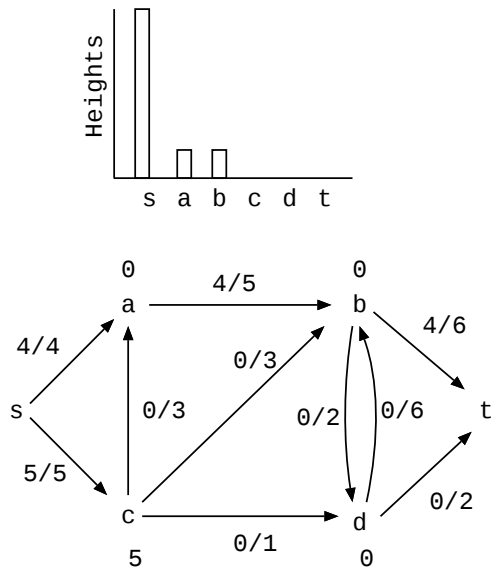
18-52: Push-Relabel Algorithms



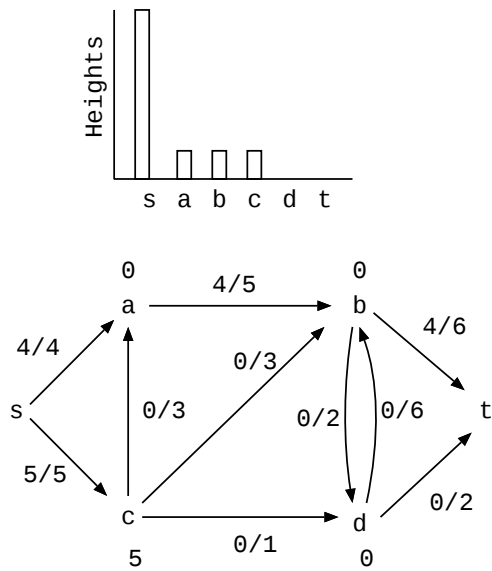
18-53: Push-Relabel Algorithms



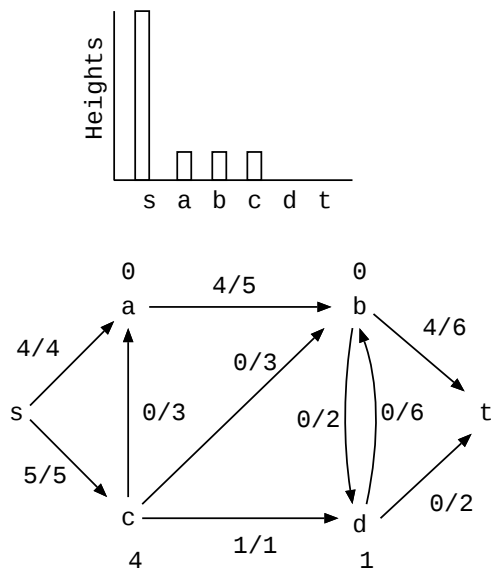
18-54: Push-Relabel Algorithms



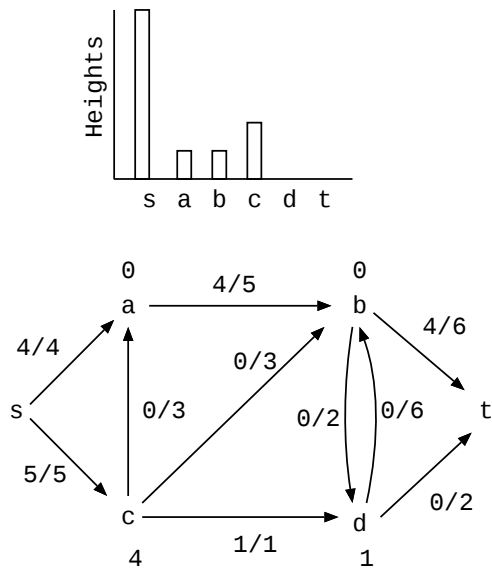
18-55: Push-Relabel Algorithms



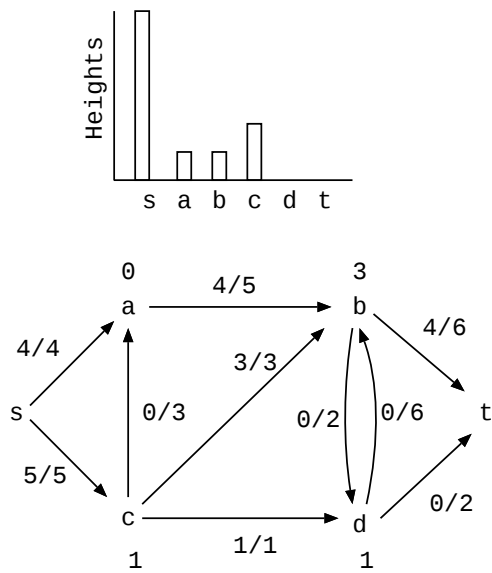
18-56: Push-Relabel Algorithms



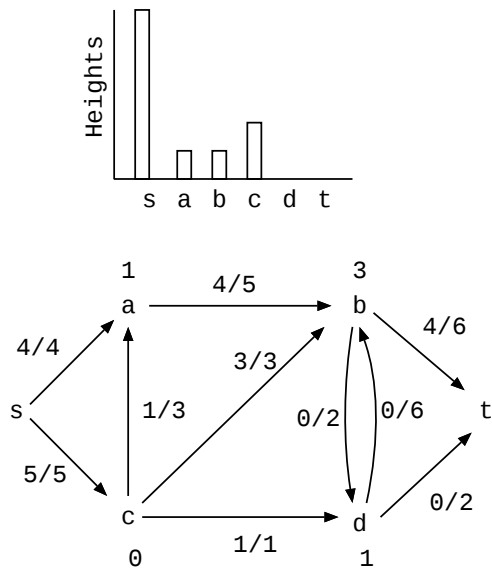
18-57: Push-Relabel Algorithms



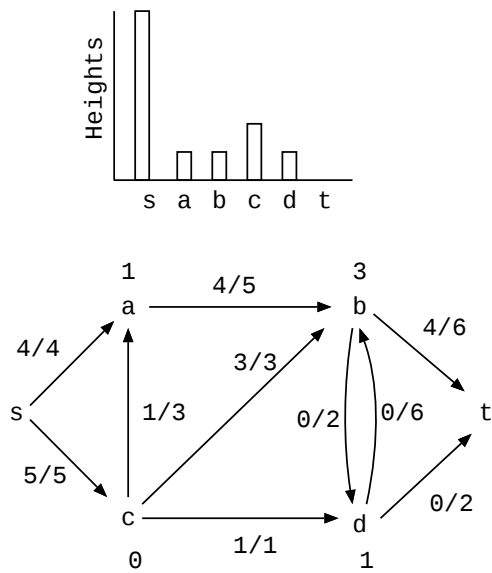
18-58: Push-Relabel Algorithms



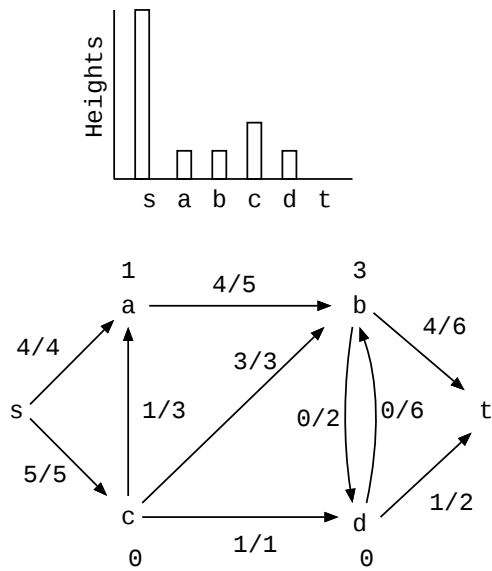
18-59: Push-Relabel Algorithms



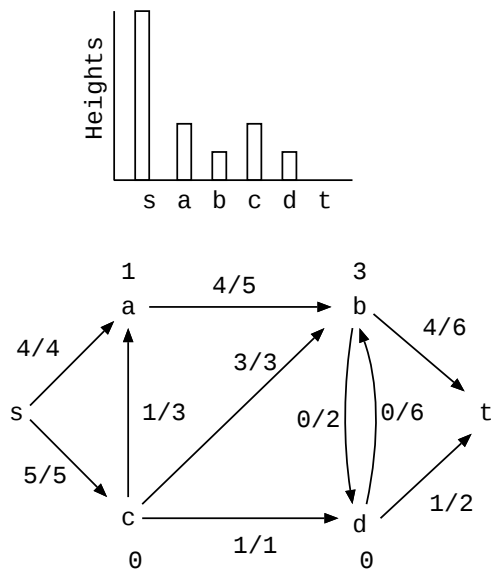
18-60: Push-Relabel Algorithms



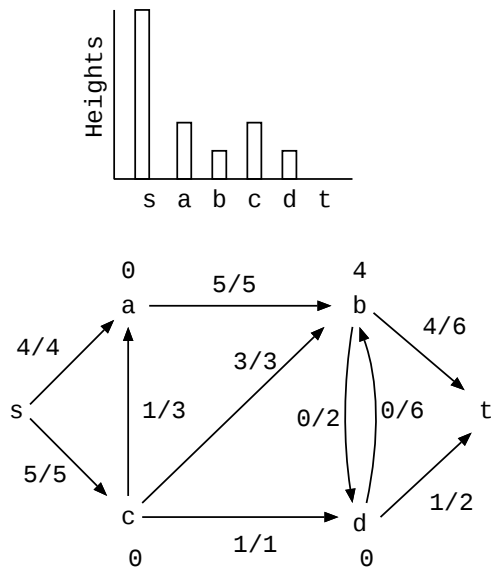
18-61: Push-Relabel Algorithms



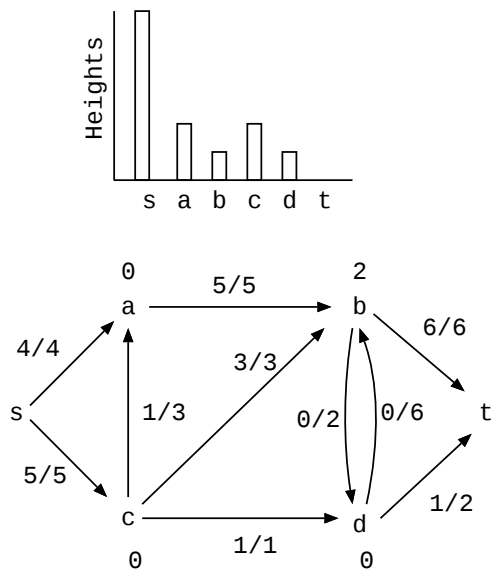
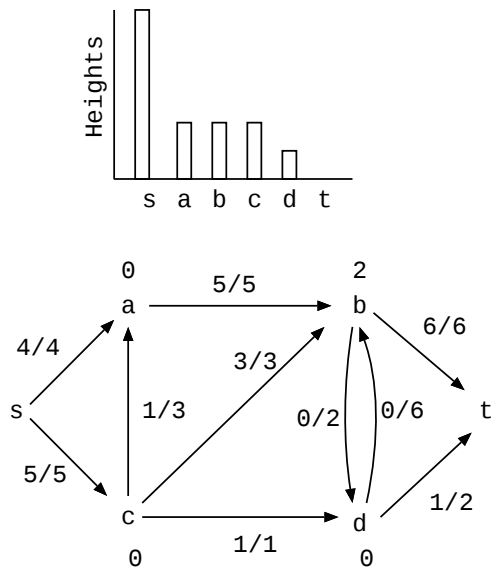
18-62: Push-Relabel Algorithms

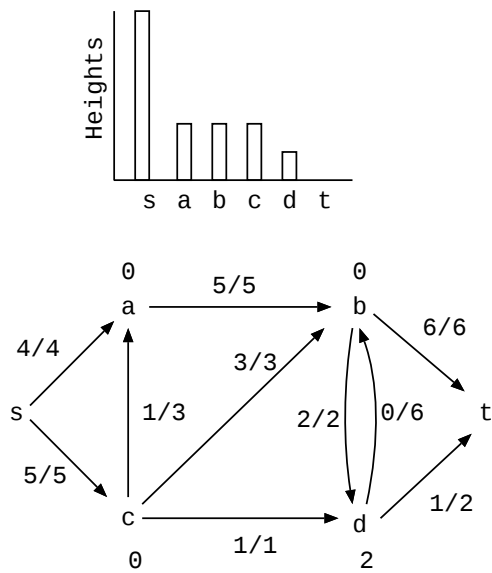


18-63: Push-Relabel Algorithms

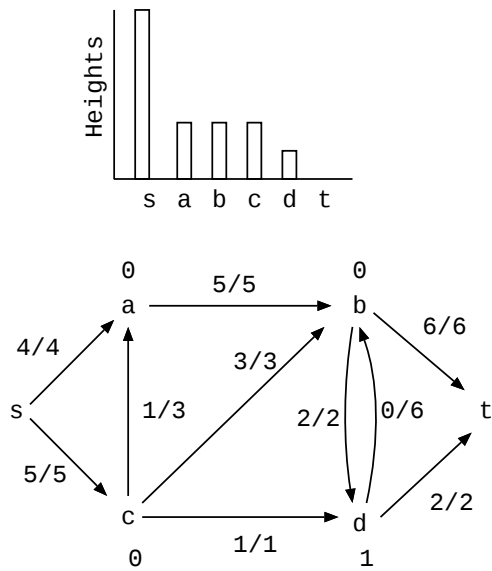


18-64: Push-Relabel Algorithms

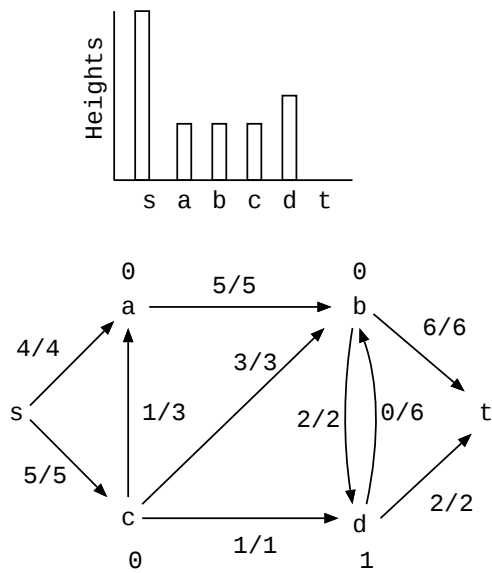
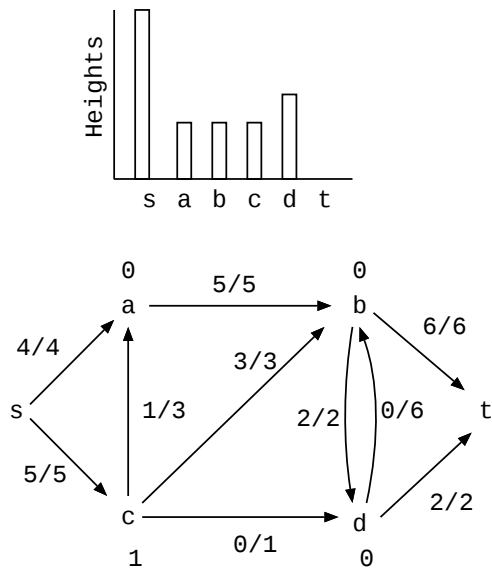
18-65: **Push-Relabel Algorithms**18-66: **Push-Relabel Algorithms**

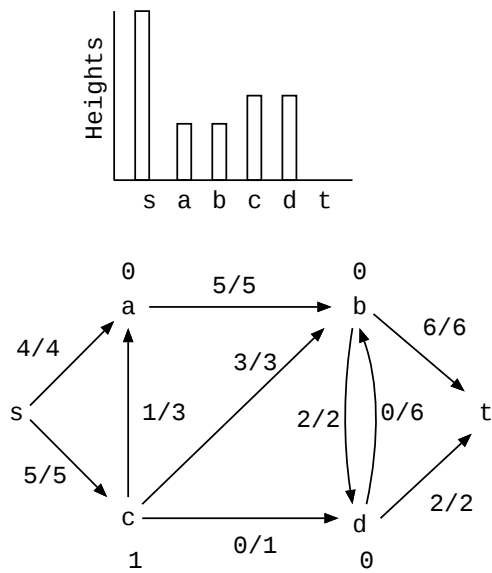


18-67: Push-Relabel Algorithms

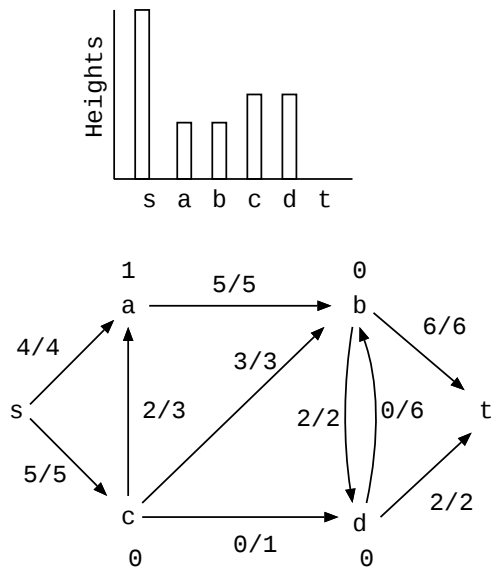


18-68: Push-Relabel Algorithms

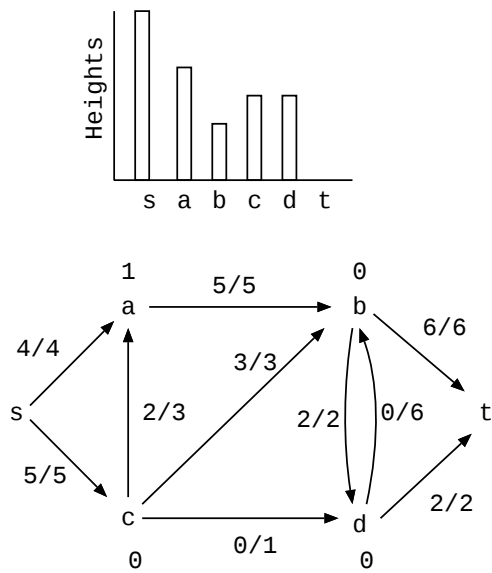
18-69: **Push-Relabel Algorithms**18-70: **Push-Relabel Algorithms**



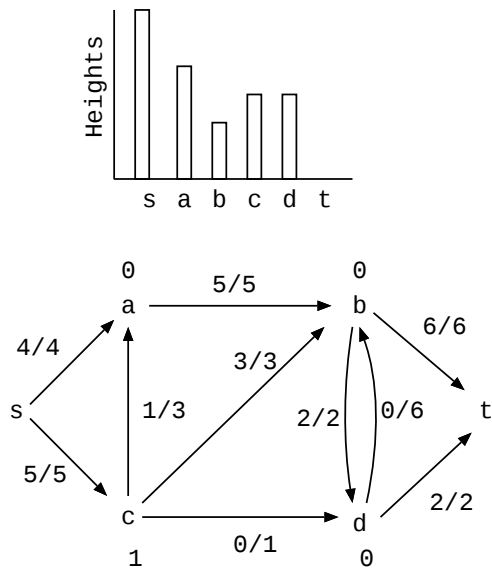
18-71: Push-Relabel Algorithms



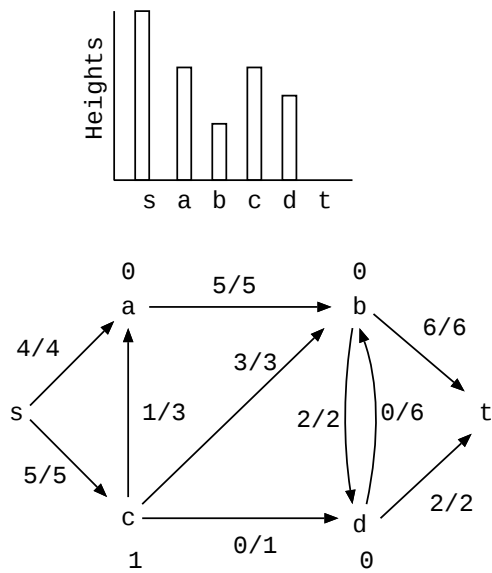
18-72: Push-Relabel Algorithms



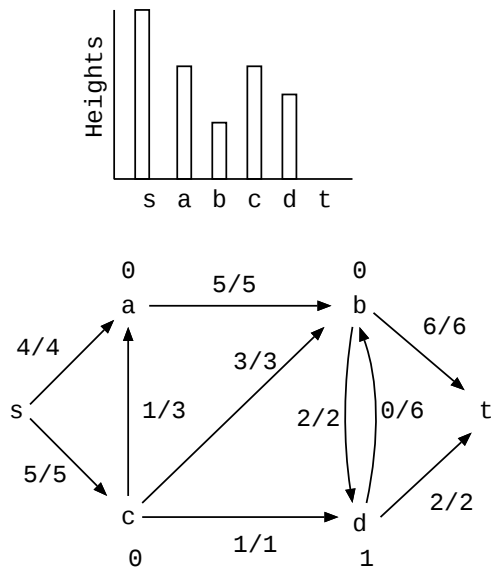
18-73: Push-Relabel Algorithms



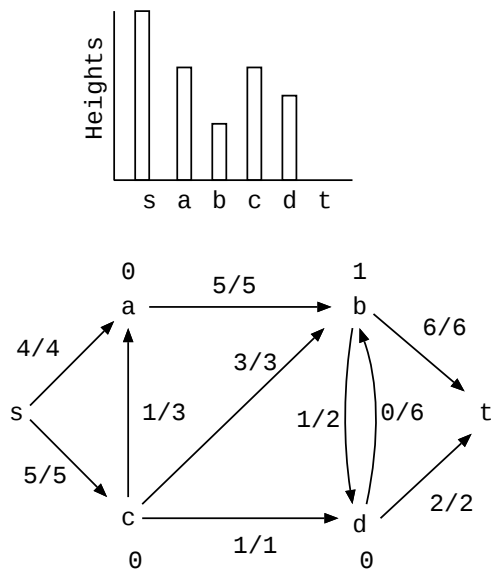
18-74: Push-Relabel Algorithms



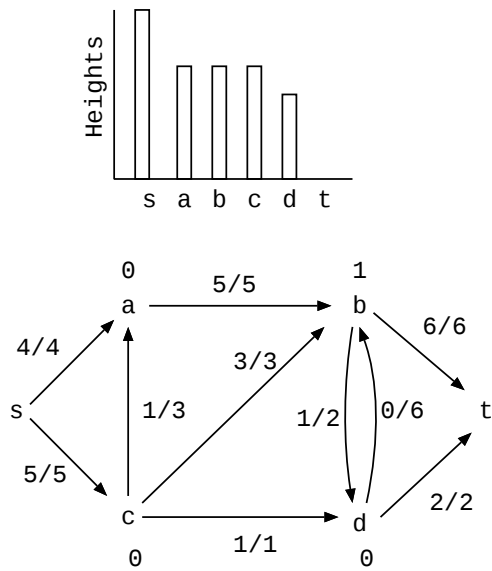
18-75: Push-Relabel Algorithms



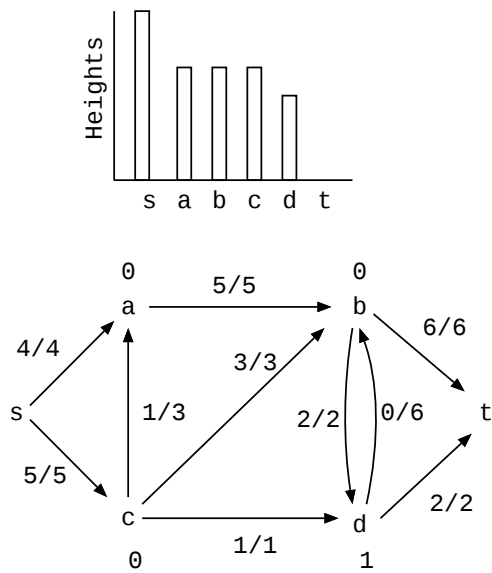
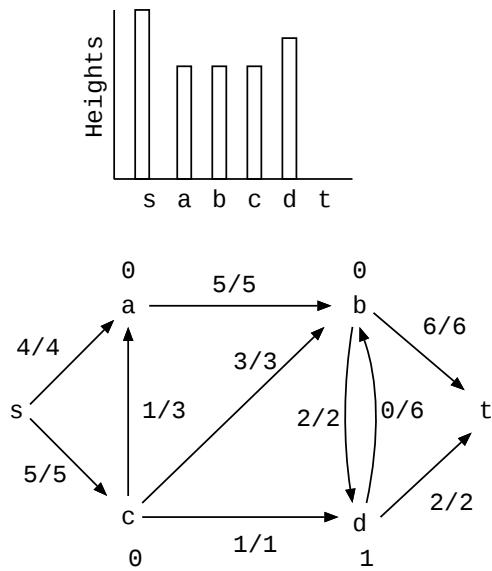
18-76: Push-Relabel Algorithms

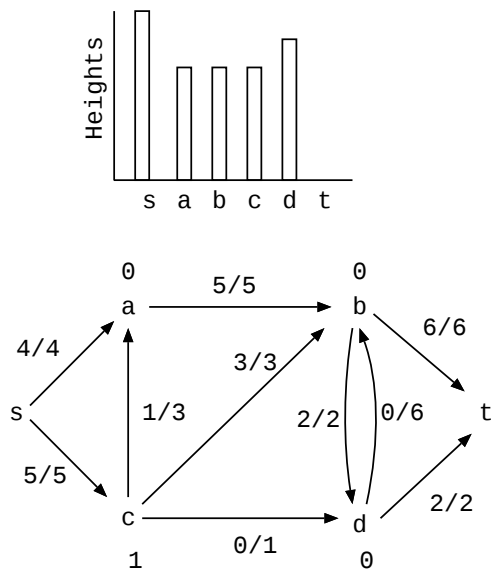


18-77: Push-Relabel Algorithms

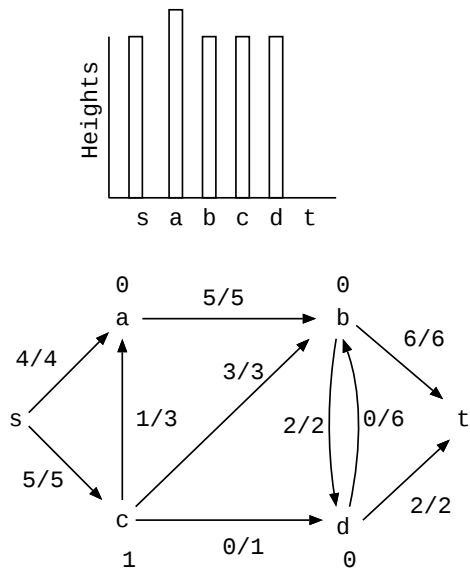


18-78: Push-Relabel Algorithms

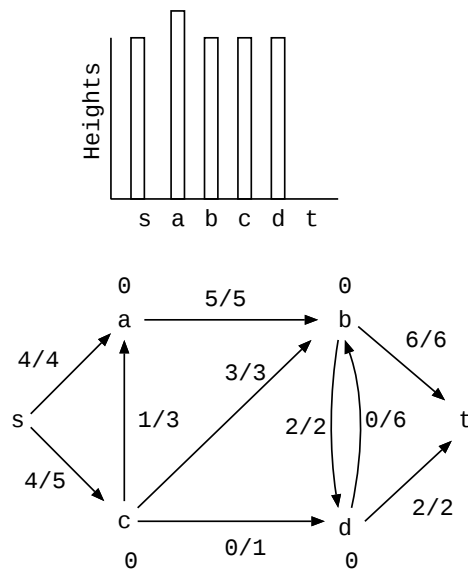
18-79: **Push-Relabel Algorithms**18-80: **Push-Relabel Algorithms**



18-81: Push-Relabel Algorithms



18-82: Push-Relabel Algorithms

18-83: **Push-Relabel Algorithms**Push( $u, v$ )

Applies when:

 $u$  is overflowing $c_f(u, v) > 0$  $h[u] = h[v] + 1$ 

Action:

Push  $\min(\text{overflow}[u], c_f(u, v))$  to  $v$ 18-84: **Push-Relabel Algorithms**Relabel( $u$ )

Applies when:

 $u$  is overflowingFor all  $v$  such that  $c_f(u, v) > 0$  $h[v] \geq h[u]$ 

Action:

 $h[u] \leftarrow h[u] + 1$ 18-85: **Push-Relabel Algorithms**Push-Relabel( $G$ )Initialize-Preflow( $G, s$ )while there exists an applicable push/relabel  
implement push/relabel18-86: **Push-Relabel Algorithms**Push-Relabel( $G$ )Initialize-Preflow( $G, s$ )

while there exists an applicable push/relabel  
implement push/relabel

- Pick the operations (push/relabel) arbitrarily, time is  $O(|V|^2 E)$ 
  - (We won't prove this result, though the proof is in the book)
- Can do better with relabel-to-front
  - Specific ordering for doing push-relabel
  - Time  $O(|V|^3)$ , also not proven here, proof in text